Extra structures on 3-manifolds
via extra structures on spines

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## Plan

1. Triangulations and special spines of (oriented) 3-manifolds
2. Branched special spines, the normal flow, and the maw
3. Closed combed 3-manifolds [BP1997]
4. Spin 3-manifolds [BP1997]
5. Generic flows on 3-manifolds [P2012]
6. Spin structures via arbitrary spines [BP2013]

## 1. Triangulations and special spines

### 1.1. Triangulations

$M$ compact 3-manifold with $\partial$ (possibly $\emptyset)$

An (ideal) triangulation of $M$ is a realization of the interior of $M$ minus some points as
(1) Take some copies of the standard 3 -simplex
(2) Glue together the faces in pairs via simplicial maps
(3) Remove the vertices

OR a realization of $M$ minus some disjoint open balls as
(1) Take some copies of the standard 3 -simplex
(2) Glue together the faces in pairs via simplicial maps
(3') Remove open regular neighbourhoods of the vertices


For oriented $M$ :
face-pairings should be orientation-reversing

Often sphere components of $\partial M$ are forbidden $\Rightarrow$ every triangulation defines a unique $M$
and perhaps

- No balls removed if $\partial M \neq \emptyset$
- One ball removed if $M$ is closed


### 1.2. Spines

$P \subset M$ is a spine of $M$ if for $N=(M$ minus some balls $)$

- $N \searrow P$
- $N \backslash P \cong(\partial N) \times(0,1]$
- $N \cong U_{N}(P)$
(equivalently)

And perhaps

- $N=M \quad$ if $\partial M \neq \emptyset$
- $N=(M$ minus one ball) $\quad$ if $M$ is closed


### 1.2. Special polyhedra

$P$ is special if

1. Locally it appears as

regions
edges

vertices
2. Edges are segments
3. Regions are discs

### 1.4 Duality

## Fact

\{triangulations of 3-manifolds $\}$

$$
\downarrow \text { duality }
$$

\{thickenable special polyhedra\}

[BP1995] (combinatorial) orientation of a special polyhedron
Fact \{triangulations of oriented 3-manifolds\}

$$
\begin{array}{cl}
\uparrow \text { duality } & \text { (orientable } \Rightarrow \text { thickenable) } \\
\{\text { oriented special polyhedra }\} &
\end{array}
$$

## 2. Branched spines, normal flow, maw

### 2.1. Branching

$P$ oriented special polyhedron, $\mathcal{T}$ dual triangulation A branching is

- An orientation for the regions of $P$ such that no edge of $P$ is induced 3 times the same orientation by the 3 incident regions
- An orientation for the edges of $\mathcal{T}$ such that the boundary of a triangle of $\mathcal{T}$ is never a cycle
(equivalently)


YES


## Fact Some $P$ 's do not admit any branching

Smoothing along edges induced by a branching

(and orientation of edges)

Fact The smoothing extends at vertices


Spine



Triangulation


A branched triangulation


### 2.2. The normal flow $\nu$

$P$ branched (Ishii) positive normal flow $\nu(P)$ on $U(P)$

concave
tangency to $\partial$

At vertices: a flow-line is doubly tangent to $\partial$

### 2.2. The maw $\nu$

$P$ branched
(Christy) descending field $\mu(P)$ on 1-skeleton $S(P)$ of $P$

$\nu$ and $\mu$ near a vertex


## 3. Closed combed 3-manifolds [BP1997]

Combinatorial realization of the set of pairs $(M,[v])$ with

- $M$ closed oriented
- $v$ non-zero vector field on $M$
- $[v]$ homotopy class (through non-zero vector fields)

Objects $P$ oriented branched special polyhedron with

$$
\begin{aligned}
& \partial U(P) \cong S^{2} \text { and } \\
& \nu(P) \text { near } \partial U(P) \text { given by }
\end{aligned}
$$



## Reconstruction

cap $\partial U(P)$ with


Moves branched versions of the Matveev-Piergallini 2-3 move



Easy extension with same techniques

- allow $\partial M \neq \emptyset$
- allow $v$ to have concave tangency to $\partial M$
- consider homotopy fixed on $\partial M$


## 4. Spin 3-manifolds [BP1997]

Combinatorial realization of the set of pairs $(M, s)$ with

- $M$ oriented
- $s$ spin structure on $M$

Objects $(P, \beta)$ with

- $P$ oriented branched special polyhedron
- weight $\beta \in C^{1}(P ; \mathbb{Z} / 2 \mathbb{Z})$ such that $\delta \beta$ is the obstruction to extending $(\nu(P), \mu(P)$ ) from $S(P)$ to $P$

Reconstruction Use $\beta$ to extend $(\nu(P), \mu(P))$ from $S(P)$ to $P$

## Moves

- Add 1-coboundaries to $\beta$
- Weighted and branched versions of the MP move


Transition points


Transition orbits

concave-to-convex

convex-to-concave

### 5.1. Combinatorial realization - objects

Set of pairs $(M,[v])$ with

- $M$ oriented compact with $\partial$
- $v$ non-zero vector field on $M$ generic along $\partial M$
- $[v]$ homotopy class through generic fields
( $\Rightarrow$ configuration on $\partial M$ evolves isotopically)

Objects $P$ compact polyhedron

- locally

- oriented along edges
- oriented branching along edges

- boundary condition (discussed below - no cellularity!)


### 5.2. Reconstruction

Theorem Each $P$ as above thickens to unique $(U(P), \nu(P))$ with

- $P$ a spine of $U:=U(P)$
- $\nu:=\nu(P)$ positively normal to $P$
- $\nu$ generic on $\partial U$
- Transition orbits of $\nu$ not elsewhere tangent to $\partial U$
- Each orbit of $\nu$ tangent to $\partial U$ in at most two points, and transversely if so

- All orbits of $\nu$ go from $\partial U$ to $\partial U$
- Topological thickening


Unique because trivial $I$-bundle on each region

- Smooth thickening at edges and $\partial$-edges

- Smooth thickening at vertices

- Smooth thickening at spikes


Extra condition on objects $(U, \nu)$ must include at least one


Reconstruction cap $(U, \nu)$ with


## Proposition Reconstruction well-defined



Proposition Reconstruction surjective
I We want to obtain a given $(M, v)$ by capping $(U, \nu)$ with

- $\nu$ generic on $\partial U$
- Transition orbits of $\nu$ not elsewhere tangent to $\partial U$
- Each orbit of $\nu$ tangent to $\partial U$ in at most two points, and transversely if so
- All orbits of $\nu$ go from $\partial U$ to $\partial U$
* Choose $U$ as $M$ minus a "very big" (trivially combed ball)
 achieving first and last condition

Other two conditions true up to homotopy

II Given $(U, \nu)$ find $P$ with $U=U(P)$ and $\nu=\nu(P)$

* in-backward $P$ : in-region of $\partial U$ union orbits to concave or transition points
* out-forward $P$ : out-region of $\partial M$ union orbits from concave or transition points


They are the same and they work

Birth of vertices


## Birth of spikes


out-for

### 5.3. Moves

- $0 \leftrightarrow 2$ sliding moves

- $2 \leftrightarrow 3$ sliding moves

- spike-sliding moves



## Idea of proof

I Express homotopy of $\partial$-to- $\partial$ fields on $U=(M$ minus trivially combed ball) as composition of elementary catastrophes reading effect on in-backward or out-forward spines

II Express isotopy of trivially combed ball as composition of elementary catastrophes reading effect on in-backward or out-forward spines

Fact Moves from II same as those from I

Catastrophe I. 1
Orbit twice concavely tangent to $\partial U$ but not transversely Effect $0 \leftrightarrow 2$ sliding moves

Catastrophe I. 2
Orbit thrice transversely and concavely tangent to $\partial U$
Effect $2 \leftrightarrow 3$ sliding moves

Catastrophe I. 2
Transition orbit also concavely tangent to $\partial U$
Effect Spike-sliding moves

## 6. Spin structures via arbitrary spines

[BP1997] Combinatorial presentation of

$$
\{(M, s): s \text { spin structure on } M\}
$$

via branched spines - not all spines admit branching
Idea [BP2013] A weaker version of branching that exists on every $P$
still allows to define $\nu(P), \mu(P)$ on $S(P)=4$-valent gluing graph of triangulation dual to $P$

Pre-branching $\omega$ on $P$ is an orientation of $S(P)$ with 2 edges in and 2 out at each vertex

Existence Express $S(P)$ as union of cycles

Weak branching $b$ compatible with pre-branching $\omega$ is a branching at each vertex inducing $\omega$


Graphic encoding


## Proposition

$\omega$ pre-branching on $P \quad b$ compatible weak branching

- They allow to define $\varphi(P):=(\nu(P), \mu(P))$ on $S(P)$
- The obstruction $\alpha(P, \omega, b) \in C^{1}(P ; \mathbb{Z} / 2 \mathbb{Z})$
to extending $\varphi(P)$ on $P$
can be computed explicitly
- $\varphi$ and $\alpha$ are additive with respect to edge summation


Idea $\quad \nu, \mu$ defined at vertices

- obvious extension along branched edges (colour 0)
- extension along unbranched edges (colour $\pm 1$ )

- extend $\nu$ vertical
- extend $\mu$ horizontal adding a full twist


## Obstruction computation

 $\alpha(P, \omega, b)$ on $R$ is a sum of contributions in $\frac{1}{2} \mathbb{Z} / 2 \mathbb{Z}$ (with final sum in $\mathbb{Z} / 2 \mathbb{Z}$ )- from vertices - requires orientation of $\partial R$

- from edges



## Proposition

$[\alpha(P, \omega, b)]=0 \in H^{2}(P ; \mathbb{Z} / 2 \mathbb{Z})$ and there exists

$$
\left\{\beta \in C^{1}(P ; \mathbb{Z} / 2 \mathbb{Z}): \delta \beta=\alpha(P, \omega, b)\right\} \xrightarrow{s} \operatorname{Spin}(M)
$$

with $s\left(\beta_{0}\right)=s\left(\beta_{1}\right) \Leftrightarrow\left[\beta_{0}+\beta_{1}\right]=0 \in H^{1}(P ; \mathbb{Z} / 2 \mathbb{Z})$
$\beta \in C^{1}(P ; \mathbb{Z} / 2 \mathbb{Z}) \quad$ weight

## Theorem

$s\left(P_{0}, \omega_{0}, b_{0}, \beta_{0}\right)=s\left(P_{1}, \omega_{1}, b_{1}, \beta_{1}\right) \Leftrightarrow \ldots$ moves

- $P, \omega, b$ fixed, $\beta$ varies: $H^{1}(P ; \mathbb{Z} / 2 \mathbb{Z})$
- $P, \omega$ fixed, $b$ changes: explicit local moves at vertices

$\pm 1 \in \mathbb{Z} /$ 3Z $e d g e ~ c o l o u r s ~ \quad ~ 1 \in \mathbb{Z} / 2 \mathbb{Z}$ weight
- $P$ fixed, $\omega$ varies: one global move (circuit)

- $P$ varies: weighted versions of 2-3 and bubble moves

Issue Replace global move by (semi-)local moves
Idea Allow branching to be "temporarily" arbitrary

- Start with weak branching $b$ compatible with pre-branching $\omega$
- Change branching at each vertex getting another $b^{\prime}$ compatible with some other $\omega^{\prime}$
- On some edges this will give

- To treat the change locally we need graphs encoding arbitrary branchings (even if globally we only want weak $\rightarrow$ weak changes)
- New edges

$\tau$ transposition
- New weighted vertex moves
- New summation rules for weighted edges
- These rules are not associative for arbitrary branchings
- When applied to weak $\rightarrow$ weak transitions they give well-defined result
- The new weighted vertex moves when applied to weak $\rightarrow$ weak transitions generate the circuit move under the new summation rules
- Same weighted 2-3 and bubble moves

