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ON 3-MANIFOLDS UP TO BLOWING-UP

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INTRODUCTION

This paper has been expressly written for these Proceedings. It contains essentially the text of my talk, together with the report of some facts occurred after a first version entitled "Classification of 3-manifolds up to blowing-up and existence of rational real algebraic structures"

containing complete proofs of the main results has circulated .

I was originally motivated , actually many years ago , to introduce and study smooth manifolds up to blowing-up along smooth centres , by an old question posed by J.Nash. In his pioneristic paper [Na] he asked , among other , if every compact closed connected smooth manifold of dimension n admitted any structure of real algebraic variety birationally equivalent to S^n (see also [v]) . As blowing-up along non singular centres is the basic construction in algebraic geometry to produce birationally equivalent varieties , and as this construction naturally extends to the smooth case as blowing-up along smooth centres , it suggested to me , by analogy , to consider the following equivalence relation on the set ${\tt V}_n$ of compact closed connected smooth manifolds of dimension n

1.1 DEFINITION X,Y=V are saied to be $\underline{\text{m-equivalent}}$ if there exists a finite sequence :

$$X=M_0 \stackrel{\longleftrightarrow}{\leftarrow} M_1 \stackrel{\longleftrightarrow}{\leftarrow} M_2 \stackrel{\longleftrightarrow}{\leftarrow} \dots \stackrel{\longleftrightarrow}{\leftarrow} M_k = Y$$

where each \leftrightarrow is either a diffeomorphism or a blowing-up (or down) along a smooth centre (i.e. along a manifold N=V $_{\rm m}$, m<n , eventually embedded in M $_{\rm i}$ or in M $_{\rm i+1}$) .

In other words we mean each blowing-up (down) as a simple modification and we consider the relation generated by diffeomorphisms and such simple modifications .

Thus a smooth analogous of Nash's question arises: is every $X_{\in}V_n$ m-equivalent to S^n ? Probably more reasonably , one could ask: how does the quotient set $V_n/_m^{\sim}$ look?

1.2 REMARK The relationship between Nash's question and its smo oth analogous should be seen just at the analogy level . The <u>implications</u> between them is a subtler matter. Let $X \in V_n$ be a non singular projective real algebraic variety birationally equivalent to S^n . Are X and S^n m-equivalent as smooth manifolds ? An answer should presumably make use of Hironaka's theorem on the resolution of singularities. However, even among people having familiarity with Hironaka's work , I have encountered two attitu des : someone seems to consider such a positive answer as a "moral" corollary of Hironaka proof; someother seems to be much more prudent; shortly I did not get a definitive answer. On the other hand , we shall see in the present paper that even in low dimension , the fact that ${\tt X}{\in}{\tt V}_n$ is m-equivalent to ${\tt S}^n$ allows only a weak answer to Nash's question (in fact the best pos sible) : actually Nash asked for non singular real algebraic models , and we get such models having in general non empty singular set .

I can state now the main results of the paper .

THEOREM A (main theorem-weak formulation) Every MeV $_3$ is m-equivalent to $\underline{s^3}$.

For the strong formulation see the next paragraph 2 .

As an application I get

THEOREM B (An answer in low dimension to Nash's question) Every MeV_3 is homeomorphic to some affine real algebraic variety M', having, in general, non empty singular set Σ , and containing a proper algebraic subset Y ($\Sigma \subset Y$) such that M'-Y is algebraically isomorphic to a Zariski open set of S³.

The analogous results for \mathbf{V}_2 hold in a easier way .

Actually we can obtain some more precision : we may get Σ of dimension 1 (0 for V_2) and the homeomorphism as a "stratified smooth isomorphism" with respect to the stratification $(M'-\Sigma, \Sigma)$ of M'...

Moreover, the singularities seem to be not eliminable, in the general case; for example, in dimension 2:

a non singular rational real algebraic surface in ${\rm V_2}$ is necessarily homeomorphic to ${\rm S}^2$ or to the 2-torus , providing it is orientable (see[Kh] and also [S]) .

The case of V_3 was the first interesting open one; for V_2 the result is an easy consequence of the classification of surfa ces up to diffeomorphism . Moreover , it was not hopeless : a general well-known method to construct all the manifolds of V3 (that is via surgery along framed links in S^3 or in $S^2\tilde{x}S^1$, the twisted s^2 -bundle over s^1 , according to the orientability or non-orientability) looked very suited to approach the problem : in fact one had , in particular , to blow-up along embedded circles. It was a nice fact (but actually not so hard , all one needed is contained in the simple lemma 3.1. below) to remark that the well-known Kirby's calculus on framed links , which preserves the diffeomorphism type , could be quite naturally extended to a very "flexible" m-calculus preserving the m-equivalence type . I remar ked it with Alexis Marin; using it we constructed several non-trivial examples of 3-manifolds m-equivalent to s^3 (enough to conjecture the main result) ; but after some fruitless attempts we were contented to collect our remarks (not so strong in our opinion) in the note published at the Dipartimento di Mat. of Pisa ([BM]) .

It has turned out that essentially the same path had been followed , independently and with the same motivations , by S.Akbulut who also remarked the m-calculus and used it to produce examples ; this is what one can deduce from the Abstract of A.M.S. (1/30/1987832-57-118).

Since 1987 no progress had been made . On last September I was aware of Nakanishi's paper ([N]) concerning (unframed) links in S^3 up to Fox congruences: I realized

soon that his result for the congruence mod(2,1), together with the m-calculus actually gave a proof of the main theorem in the orientable case. By a non immediate extra-work not depending on Nakanishi's theorem in[N], I reduced the non-orientable case to the orientable case, finally completing the proof.

This is the proof I had presented in my talk .

While it has to my eyes the nice feature of the first complete solution of a longstanding problem I had been interested in from the very beginning of its own formulation , however it could be considered not completely satisfactory : one could try to find a more self-contained proof , relaxing the dependence on [N]; moreover Nakanishi's theorem , while being very nice , is largely proved by "pictures" in 2-dimensional space of links projections . One could look for a more conceptual and purely 3-dimensional proof .

After our symposium I had realized that the argument of the reduction from the non-orientable to the orientable case , could be used to get a proof of the main theorem , at least in its weak formulation , without using the m-calculus and Nakanishi's result ; but it was not yet completely satisfactory .

Finally I received a letter (dated 3 Nov.1989) from Alexis Marin , containing several friendly comments on my paper and a sketch of a proof , extracting the basic 3-dimensional meaning of the business , not using [N] , which I consider the <u>definitive</u> proof as it is short and clean . I will reproduce this sketch .

On the other hand , I believe that the formulation of the results in terms of m-calculus (see the parag. 4 and 5), allowed by the use of [N] , maintains its own interest and deserves to be pointed out .

I take the occasion to thank the JSPS for giving me the occasion to spend some time in Japan , the Nagoya University and mostly Masahiro Shiota for the friendly hospitality .

2. Strong formulation of the main theorem .

Decompose $V_3 = V_3^+ \cup V_3^-$, "+" means orientable and "-" non-orientable . For every MeV3 let b=b_M= dim H_2(M,Z_2) .

In fact we shall obtain:

THEOREM A (main theorem-strong formulation for V_3^+)

For every $M_{\in}V_3^+$, there exist a link L in M and a link L' in $\#_{1 \le i \le b}$ (i.e. the connected sum of b copies of the projective 3-space) such that by blowing-up along the components of L and L' respectively one obtains diffeomorphic 3-manifolds .

Note that $\#_{i} \mathbb{P}^{3}$ is nothing else than the result of a blowing-up of S^{3} at b points .

Before stating the analogous result for V_3^- we need a definition.

2.1. DEFINITION A simple tower of blowing-up of lenght s over s^3 is obtained as follows: consider an ordered family c_1,\ldots,c_s of unknots in s^3 , looking like in this picture:



We mean that at the common point C_i and C_{i+1} have independent tangents . Then make a sequence of blowing-up :

$$S^3 = B_0 + B_1 + B_2 + \dots + B_s$$

such that C_1 is the centre of the first one π_1 , the "strict transform" of C_{i+1} in B_i (i.e. the closure in B_i of $(\pi_i \dots \pi_1)^{-1}(C_{i+1} - C_i)$) is the centre of π_{i+1} . For example $S^2 \tilde{\times} S^1$ is diffeomorphic to B_1 , $\mathbb{P}^2 \times S^1$ to B_2 .

THEOREM A (main theorem-strong formulation for V_3)

For every $M \in V_3$, there exist a link L in M and a link L' in Bs # ($\#_{1 \le i \le h}$ P), s+h=b, every component of L and L' being a non-reversing orientation circle, such that by blowing-up along the components of L and L' respectively, one obtains diffeomorphic 3-manifolds.

The proof shall give further nice corollaries . We limit to remark the following one , not at all evident a priori . Let us denote by $\underline{\text{m}}^{+}$ -equivalence the relation generated on V_3 by diffeomorphisms and blowing-up along non-reversing orientation embedded circles . In paricular no blowing-up at points is allowed . Then we have :

2.2 COROLLARY m-equivalence and m⁺-equivalence coincide on V_3 . That is every $M_{\in}V_3$ is m⁺-equivalent to S^3 .

3. The m-calculus .

Dehn surgery data on a manifold MeV consist of Δ = (C,U,m,ℓ,q/p) where : C is an embedded circle in M with U as orientable tubular neighbourhood; m and ℓ are fixed meridian and longitude in ϑ U; q/p is a rational number with (q,p)=1 and also ∞ = q/0 is allowed. The manifold M obtained from M by surgery with data Δ , is well defined (up to diffeo.) as:

$$M_{\Delta} = \overline{M-U} \cup_{h} U$$

 $h: \partial U \to \partial U$ being any diffeomorphism such that $h_{\star}([m]) = q[m] + p[\ell]$ in $\pi_1(\partial U)$. The key remark is contained in the following simple lemma .

- 3.1 LEMMA Let A,B be obtained from $M \in V_3$ by surgeries with data differring only by q/p and b/a . Let A',B' be the blowing-up of A and B respectively along C . Assume that either :
- 1) $p\equiv a\equiv 0 \mod 2$; or
- 2) $p \equiv a \equiv 1 \mod 2$ and $q \equiv b \mod 2$.

Then there exists a diffeomorphism between A' and B' which is the identity on M-U.

The proof is an easy consequence of the fact that the inverse image of U , via the blowing-up , U' say , is diffeomorphic to $\mathbb{M} \times S^1$, \mathbb{M} being the Moebius strip , and that a diffeomorphism $g:\partial U' \to \partial U'$ extends to a diffeomorphism $g:\partial U' \to U'$ if $g_*([m]) \equiv [m] \mod 2$.

By definition , a <u>framed link</u> in $M{\in}V_3$, is a link L embedded in M with a system of surgery data for each its component , with the restriction that q/p is actually equal to q/l . If a component C of a link L is contained in an embedded ball , then its framing is completely determined by an integer number , that is the linking number lk(C,C') between C and its suitable "parallel" C'.

It is well-known ([L₁],[L₂]) , that every orientable $M\in V_3^+$ is diffeomorphic to some manifold $\chi(L)$ obtained from S^3 by surgery along the components of some framed link L , and that every $M\in V_3^-$ can be ontained as such a $\chi(L)$ for some framed link in $S^2\tilde{\chi}S^1$. Such representation being not unique , Kirby's calculus on framed links , preserving the diffeomorphism type of $\chi(L)$ is well-known (we refer to [K] ,[R] , and [FR]). We consider the following extension of this calculus , called in the sequel χ -calculus , to an M-calculus preserving the M-calculus we need are :

 m_1 : the "moves" of χ -calculus;

 m_2 : introducing (or deleting) \bigcirc_2 contained in a separating 3-ball .

 m_3 : changing the framing according to lemma 3.1. In particular if the framing is given by an integer number (like in the case of links in S^3) k , then we may replace k by any k' \equiv k mod 2 .

Note that m_2 corresponds to the blowing-up at a point , because this is equivalent to make the connected sum with \mathbb{P}^3 and \bigcirc_2 is the simplest representation of \mathbb{P}^3 via framed links in \mathbb{S}^3 .

We shall denote by $\ \underline{m}_{\mbox{\scriptsize R}} - \mbox{\scriptsize calculus}$ the reduced m-calculus generated only by the moves m_1 and m_2 .

- 3.2. LEMMA $\dim H_2(\chi(L), Z_2)$ is invariant by m_R -calculus. The proof is immediate .
- 3.3. LEMMA If two framed links L,L' (for fixing the ideas in S^3 or in $S^2 \hat{x} S^1$) are related by the m-calculus, then $\chi(L)$ and $\chi(L')$ are actually m⁺-equivalent.

<u>Proof.</u> If L and L' are related by an m_3 move , the they are evidently m^+ -equivalent. Then \bigcirc_2 is m^+ -equivalent to \bigcirc_0 which is diffeomorphic to $S^2 \times S^1$. Then it is easy to see that $S^2 \times S^1$ is m^+ -equivalent to $(S^2 \times S^1) \# (S^2 \times S^1) \# (S^2 \times S^1) \# (S^2 \times S^1)$, that is to $B_1 \# B_1$ (with the notation of def. 2.1.), thus it is m^+ -equivalent to S^1 .

4. Formulation of THEOREM A in terms of m-calculus.

For every framed link L in S 3 , set b=b_T= dim H_2(χ (L),Z_2) .

THEOREM C + Framed links in S up to m_R-calculus are classified by b_L . Every link L is m_R -related to the framed link:

b-times

Consequently every framed link L in S³ is related to the empty link by the m-calculus .

It is not hard that Theorem C implies Theorem A. Moreover , by lemma 3.3. we get immediately the corollary 2.2. in the orientable case .

This is a good point to recall Nakanishi's result ($\lceil N \rceil$). We shall formulate it in a convenient way to our purpose .

4.1. DEFINITION Let L be a link in S^3 . Let $H:D^2 \times [0,1] \rightarrow S^3$ be a smooth embedding such that $H \mid (S^1 \times [0,1])$ (here $S^1 = \partial D^2$) is an embedding in S^3-L . Then for every finite set $\{x_1,\dots,x_k\}{\subset}[\,0\,,1\,]$, $\cup_{i} H(S^{1} \times \{x_{i}\})$ is called a set of <u>parallel components</u> of the link $L \cup (\cup_i H(S^1 \times \{x_i\})) = L \cup P.$

Let Λ_n be the set of (unframed) links in S^3 with n components. 4.2. DEFINITION Fox congruence mod (2,1) on Λ_n is the relation generated by the following elementary "move" :

- First introduce an even number k of parallel components getting $\mathtt{L} \cup \mathtt{P} {\in} \Lambda_{n+k}$. Give all components of P the framing 1 (or -1).
- Make k Kirby's moves along the so framed components of P (forgetting the framing for L) , getting $L' \in \Lambda_n$.

If L and L' are related by a finite sequence of such moves , we say shortly that they are congruent .

4.3. DEFINITION L= $C_1 \cup \ldots \cup C_n$, L'= $C_1 \cup \ldots \cup C_n$ in Λ_n are \underline{Z}_2 -link-homologous if the linking numbers $lk(C_i, C_i) = lk(C_i, C_i)$ for i≠j .

4.4. THEOREM ([N]) L,L' $\in \Lambda_n$ are congruent if and only if they are Z₂-link-homologous. In particular every knot is congruent to the unknot.

The key remark to us is:

4.5. LEMMA The elementary move generating the congruence is composition of moves of the m_R -calculus.

<u>Proof.</u> By χ -calculus we can introduce any number of pairs of parallel components one with framing 1 , the other with -1 . By m₃ we can change 1 in -1 .

Sketch of proof of theorem C+.

It is a rather easy induction on the number of components of framed links in S³, denote it by n . If n=1 then (by 4.4.) the framed knot is m_R -equivalent either to \bigcirc_1 or \bigcirc_0 . For general n , (again by 4.4.) , we are free to work in the Z₂-link-homology class of any given link L with n components (forgetting the framing) ; considering a simple representative and reintroducing the possible framings reduced mod 2 , it is not hard , using the χ -calculus , to pass to a framed link with a strictly smaller number of components , unless we are in the final "normal form" .

This concludes the discussion in the orientable case .

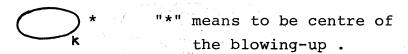
5. The non-orientable case .

We whant to prove :

5.1. PROPOSITION Every $M \in V_3$ is m-equivalent to some $M' \in V_3^+$.

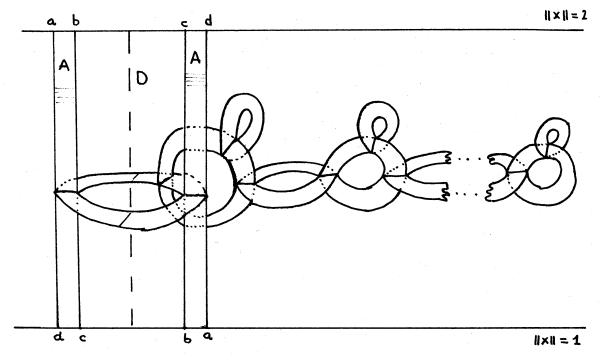
I will sketch the proof.

First it is convenient to consider two models for $s^2\tilde{\times}s^1$. One consists in considering it as B₁ (with the notation of def. 2.1.) , that is as the result of the blowing-up of s^3 along an unknot K .



The other one is obtained by identifying the boundary components of $S=\{x=(x_1,x_2,x_3)\in I\!\!R^3\,\big|\,1\le \big\|x\big\|\le 2\}$, via a dilatation followed by the reflection along the plane $\{x_2=0\}$. Thus we mean $S^2\tilde\times S^1$ as $S/_{\sim}$. Call D the inverse image of the unknot K , by the blowing-up in the former model . In $S/_{\sim}$, D can be identified with $(\{x_2=0\}\cap S)/_{\sim}$.

Then , using the finite set of generators for the mapping class group of any given non-orientable surface of fixed genus , constructed in [C] , and arguing similarly to the orientable case as made , for example,in [R] , we deduce that every MeV_3^- can be obtained by surgery along some framed link in $\text{S}^2\tilde{\times}\text{S}^1$, looking in a certain special configuration . More precisely consider the family of annuli embedded in S/~ as shown in this picture :



For simplicity S is shown "stright"; k-1 annuli looks "round and planar" in the picture and are fibred by concentric circles which are homotopically trivial in $\text{S}^{2}\tilde{\times}\text{S}^{1}$. Exactly one annulus , called A , is fibred by non-trivial circles and looks "round and planar" in the other model :



Note that A cuts only one of the other annuli (the one intersecting D) along two segments .

Every component of our special link is contained in and concentric to one of these annuli . The components on A are called of A-type , the other of N-type .

Evidently , if no A-type components do occur , then we could isotopy the link far from D and , after a blowing-down , to see it as a link in \mathbb{S}^3 . In some sense the problem is to eliminate the A-type components . We may assume that at least one of these A-type components has the property that the Moebius strip "naturally bounded" by it does not intersect the other components of the link . For the framing of such a component we have (mod 2) two possibilities : if it is 1 we can eliminate the component by $\chi\text{-calculus}$. If the framing is 0 , we use the following argument .

(in fact B_2 is the result of a blowing-up of $S^2 \tilde{\times} S^1$ along a section over S^1) are diffeomorphic and in fact diffeomorphic to $\mathbb{P}^2 \times S^1$. Using a suitable diffeomorphism , we see that the image of the remaining components of the link are contained in a copy of $\mathbb{M} \times S^1$, embedded in B_2 and look inside it like a link in special configuration , preserving the type . So we have one A-type component less and we can conclude by induction . This concludes the sketch of the proof of 5.1.

It is not hard that this proof with the one of Theorem C^+ , actually implies the theorem A^- . Using Theorem A^- , and "reversing" the proof of 5.1., one can obtain the proof of corollary 2.2. also in the non-orientable case .

Finally we can deduce the following version in terms of m-calculus on framed links in $S^2 \widetilde{\times} S^4$.

Consider the \underline{m}_E -calculus , that is the extended calculus generated by the usual m-calculus of paragraph 3 together with the further move :

" introduce or delete any A-type component with framing 0 , such that the Moebius strip naturally bounded by it does not intersect the other components " .

THEOREM C Every framed link L in $S^2 \tilde{x} S^1$ is related to the empty link by the m_E-calculus .

6. A sketch of proof of THEOREM B .

It uses arguments currently emploied in Nash-Tognoli type theorem. I refer to [AK],[BCR],[Iv],[To] for an ample account about this circle of ideas .

Let $M_{\in}V_{\mathfrak{F}}$. Use , to simplify , the strong version of the main theorem. First we may assume that the blowing-up over \mathbf{S}^3 is made along non singular algebraic centres . Thus we get a non singular projective real algebraic variety M" birationally equivalent to ${\rm S}^3$. Moreover it has the property that ${\rm H_2\,(M^n,Z_2)}$ is generated by the algebraic hypersurfaces in M" . Thus we can approximate in M" any compact smooth closed hypersurface by some non singular algebraic ones; moreover also a relative version of this fact Assume , for simplicity , that we have only one blowingdown to do in order to pass from M" to M . Let C be its smooth centre in M and D be its inverse image in M" . D is a smooth 2-torus and , by the above discussion , we may assume that D is a non singular algebraic subvariety of M" having the property that $H_1(D,Z_2)$ is generated by the algebraic curves contained in D . Give C the algebraic structure of the standard unit circle ${f S}^1$. By the so recalled assumptions on D , we know that the map $\pi \, \big| \, D \, \big| \, (\, \pi \, \text{is the blowing-down)} \, \, \text{can be approximated by rational} \,$ regular maps g: D \rightarrow S¹. Note that , topologically, M = (M" \cup C)/ π |D and that if g is close enough to $\pi \mid D$, then M and $(M" \cup C)/g$ are homeomorphic . Finally one recalls the fact that , since g is a regular rational map , the last quotient space can be realized by a (singular) real algebraic, affine variety M'and that there exists a regular rational map from M" onto M' which is an algebraic isomorphism between M"-D and M'-C .

7. A sketch of A.Marin's proof of the main theorem .

Here is the key remark:

7.1. REMARK Let C_1 and C_2 be knots in $M_{\!\!\! = \!\!\! V_3}$, making the boundary of an embedded surface F having an orientable neighbourhood in M . Then C_1 and C_2 become isotopic in a manifold M' obtained from M by some Dehn surgeries having in the data q/p of the form 2k+1/2, along circles embedded in a neighbourhood of F-($C_1 \cup C_2$) in M-($C_1 \cup C_2$).

In fact , we may assume that F is non-orientable (like the unknot in this picture bounds a Moebius strip). Then F is diffeomorphic to the connected sum of some copies of \mathbb{P}^2 , with two disks removed . Thus we can pass from F to the 2-disk with two holes by replacing some Moebius strip embedded in F by 2-disks . Actually we can realize this operation in a manifold M' obtained by Dehn surgeries of the type saied above along the base line of each Moebius strip .

Actually it is enough to prove the main theorem in the orientable case . We may assume that $M \in V_3^+$ is obtained by surgery along a framed link in s^3 having at least one component with $\underline{\mathtt{odd}}$ framing . Using the classification of odd bilinear forms over Z, and by "handle slides" (if one prefers by χ -calculus) , we may assume that the linking numbers of any pair of different components of the link , is even . Thus we can see M as the last of a sequence $S^{3}=M_{1},M_{2},...,M_{k}=M$, of 3-manifolds such that M_{i+1} is obtained from M_{i} , by a surgery along a knot C_{i} which bounds a surface F_i (not necessarily orientable) embedded in M_i. Now the proof of the main theorem is an easy consequence of the above remark and of lemma 3.1. : we see , by induction , that M is m-equivalent (in fact m⁺-equivalent) to $\#_{1 \le i \le d} \mathbb{P}^3$, where $d = \dim H_1(M, Z_2)$, that is the nullity of the bilinear form over Z_2 of the given link . Note that d= dim $H_2(M,Z_2)$, so we have obtained nothing else than Theorem \boldsymbol{A}^{+} .

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