

Orthogonal similarity  
reduction of any symmetric  
matrix into a  
diagonal-plus-semiseparable  
one with free choice of the  
diagonal

Ellen Van Camp, Raf Vandebril, Marc Van Barel  
and Nicola Mastronardi

## I. Algorithms

**Orthogonal similarity transformation** of any **symmetric matrix** into

1. **tridiagonal form** (Golub, Van Loan)
2. **semiseparable form** (Vandebril, Van Barel, Mastronardi)
3. **diagonal-plus-semiseparable form with free choice of the diagonal** (2 algorithms)

## 1. Reduction to tridiagonal form

Any symmetric matrix can be transformed into a tridiagonal one by means of orthogonal similarity transformations in order  $O(\frac{4}{3}n^3)$ .

### Definition

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## 2. Reduction to semiseparable form

Any symmetric matrix can be transformed into a semiseparable one by means of orthogonal similarity transformations in order  $O(\frac{4}{3}n^3)$ .

### Definition

When every submatrix that can be taken out of the lower-, resp. upper-, triangular part of a symmetric matrix has rank at most 1, this matrix is called a semiseparable matrix.





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| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | x |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | x | x |

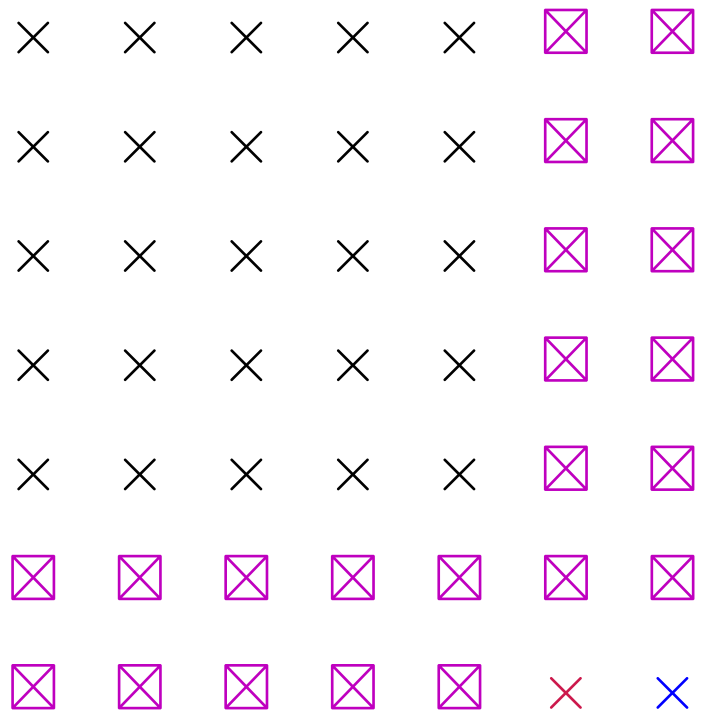
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|---|---|---|---|---|---|---|
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | x |
| 0 | 0 | 0 | 0 | 0 | x | x |

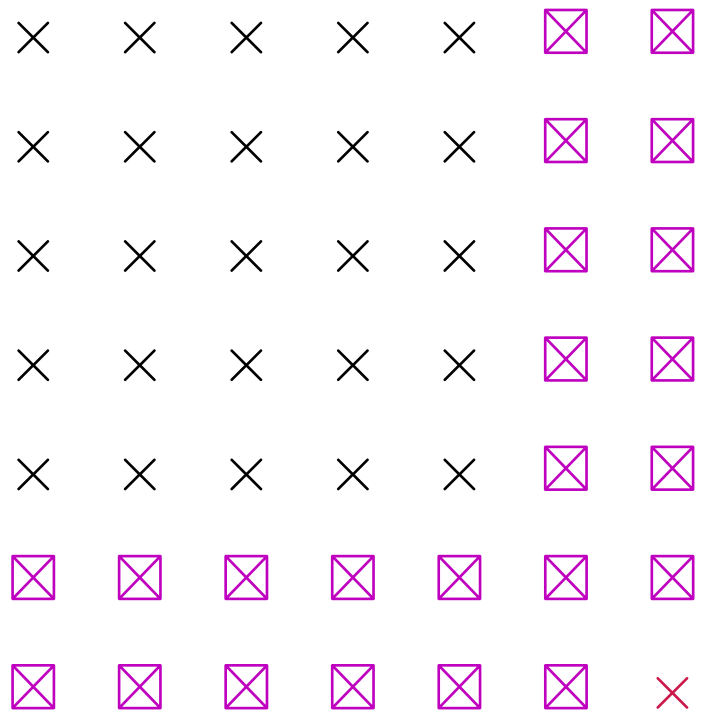
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| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | ⊗ |
| 0 | 0 | 0 | 0 | 0 | x | x |

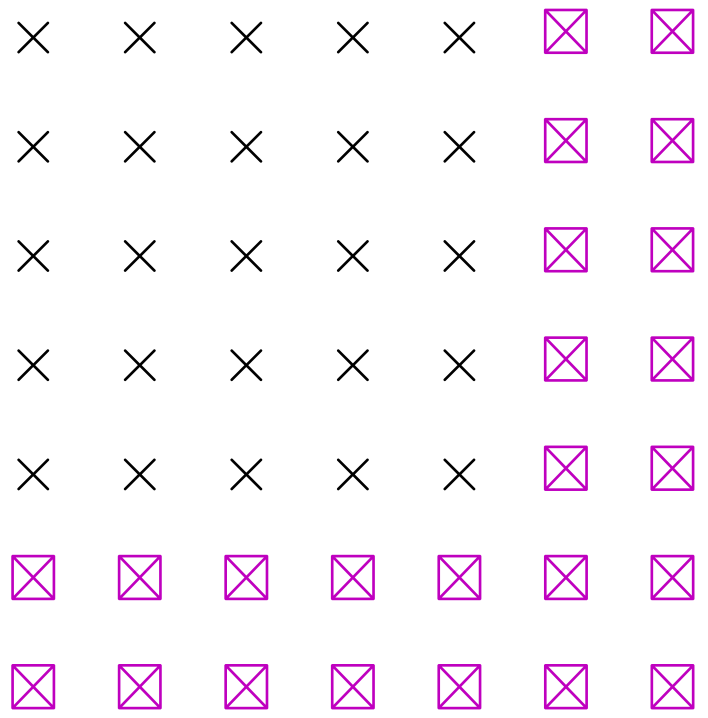


$$\begin{aligned} \begin{bmatrix} c & s \\ -s & c \end{bmatrix} \begin{pmatrix} \times \\ 0 \end{pmatrix} &= \begin{pmatrix} c \times \\ -s \times \end{pmatrix} \\ &= \begin{pmatrix} \boxtimes \\ \boxtimes \end{pmatrix} \end{aligned}$$

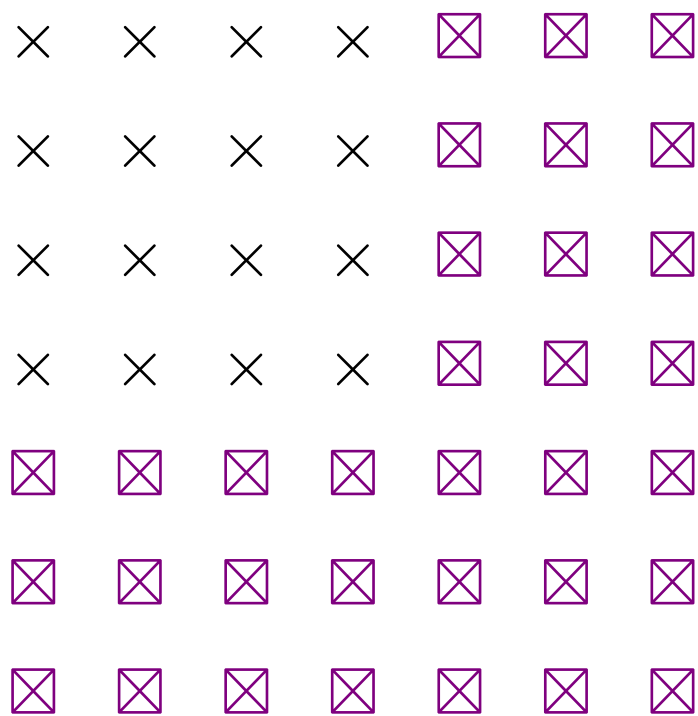
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| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
| x | x | x | x | x | x | 0 |
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| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | x | x |

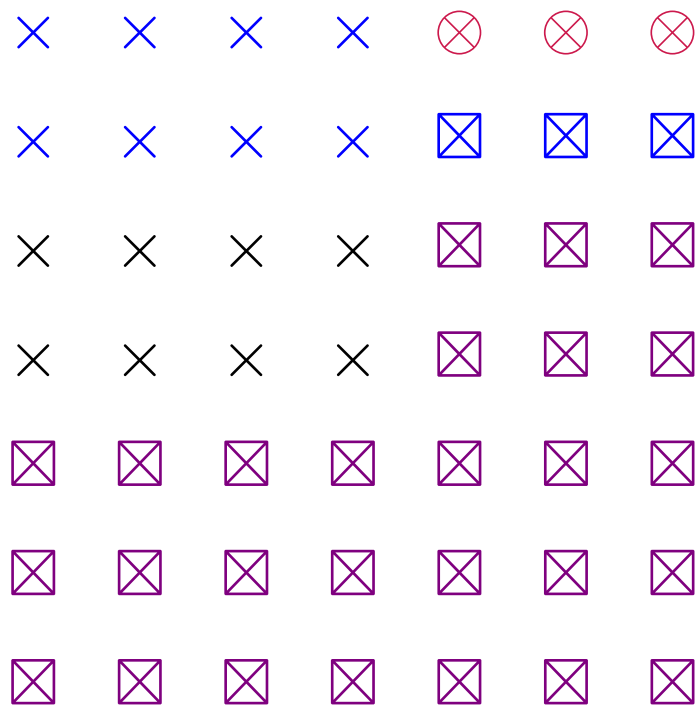






### Step 3





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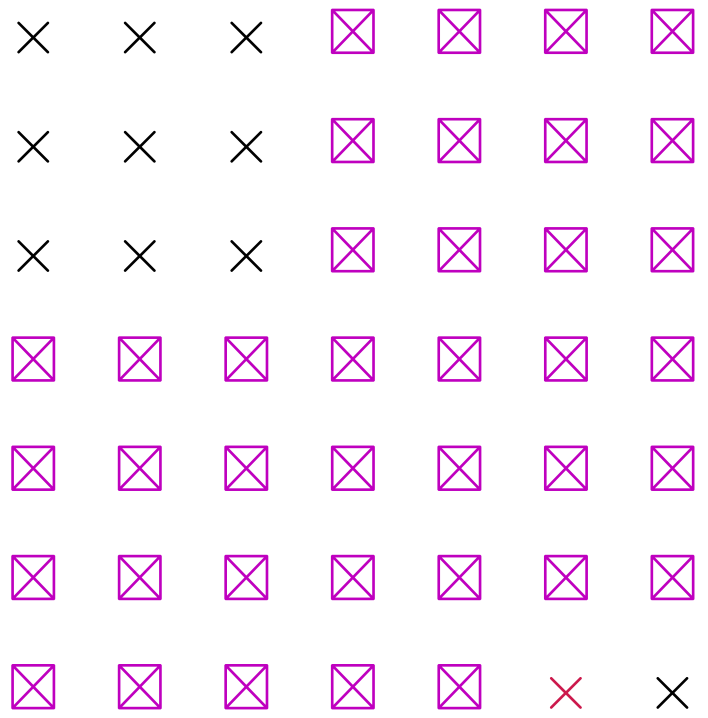
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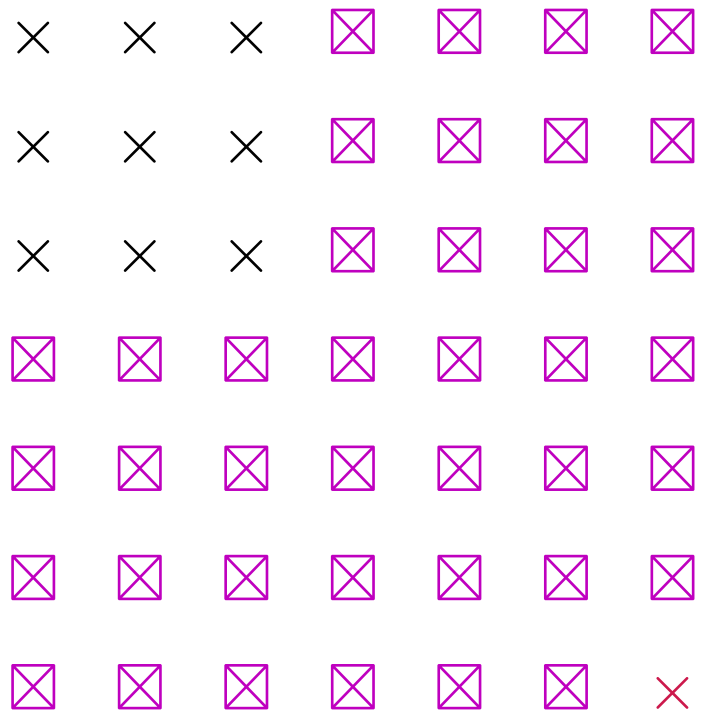


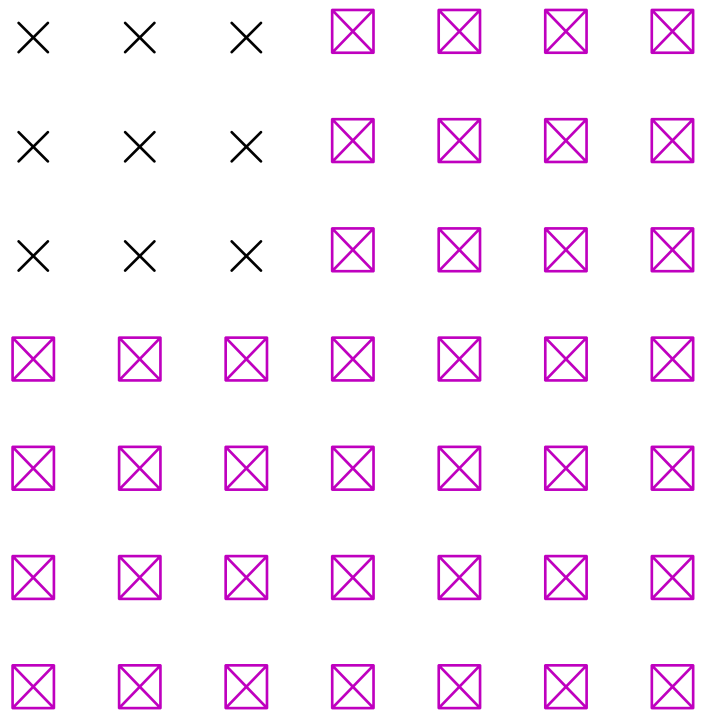
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### 3. Reduction to diagonal-plus-semiseparable form with free choice of the diagonal

Any symmetric matrix can be transformed into a diagonal-plus-semiseparable one where the diagonal can be chosen in advance, by means of orthogonal similarity transformations in order  $O(\frac{4}{3}n^3)$ .

#### Definition

The sum of a symmetric semiseparable matrix and a diagonal matrix is called a diagonal-plus-semiseparable matrix.

So choose a diagonal  $\mathbf{d} = [d_1, d_2, \dots, d_n]$ .





## Step 1

$$\begin{array}{cccccccccccccccc} \times & \times & \times & \times & \times & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \times & \times & \times & \times & \times & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \times & \times & \times & \times & \times & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \times & \times & \times & \times & \times & \times & \times & + & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \times & \times & \times & \times & \times & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \times & \times & \times & \times & \times & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \times & \times & \times & \times & \times & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & d_1 \end{array}$$

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| × | × | × | × | × | × | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0     |
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| × | × | × | × | × | × | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0     |
| × | × | × | × | × | × | × |   | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | × | × |   | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $d_1$ |

$$\begin{array}{cccccccccccccccc}
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & + & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & \times & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & d_1
\end{array}$$

$$\begin{array}{cccccccccccccccc}
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & + & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & \otimes & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & \otimes & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & d_1
\end{array}$$

## Problem

$$\begin{bmatrix} c & s \\ -s & c \end{bmatrix} \begin{pmatrix} 0 & 0 \\ 0 & d_1 \end{pmatrix} \begin{bmatrix} c & -s \\ s & c \end{bmatrix} = \begin{pmatrix} s^2 d_1 & csd_1 \\ csd_1 & c^2 d_1 \end{pmatrix}$$

$\Rightarrow$  ???

## Solution

$$\begin{aligned} & \begin{bmatrix} c & s \\ -s & c \end{bmatrix} \begin{pmatrix} d_1 & 0 \\ 0 & d_1 \end{pmatrix} \begin{bmatrix} c & -s \\ s & c \end{bmatrix} \\ = & \begin{bmatrix} c & s \\ -s & c \end{bmatrix} d_1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{bmatrix} c & -s \\ s & c \end{bmatrix} \\ = & \begin{pmatrix} d_1 & 0 \\ 0 & d_1 \end{pmatrix} \end{aligned}$$

$$\begin{array}{cccccccccccccccc}
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & + & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & \otimes & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & \otimes & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & d_1
\end{array}$$

$$\begin{array}{cccccccccccccccc}
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & + & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & \times & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \times & \times & + & \otimes & & 0 & 0 & 0 & 0 & 0 & 0 & d_1 & 0 \\
0 & 0 & 0 & 0 & 0 & \otimes & \times & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & d_1
\end{array}$$



|   |   |   |   |   |   |   |   |   |   |   |   |   |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|---|---|-------|-------|---|
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0     | 0     | 0 |
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0     | 0     | 0 |
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0     | 0     | 0 |
| × | × | × | × | × | ⊗ | ⊗ | + | 0 | 0 | 0 | 0 | 0 | 0     | 0     | 0 |
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | $d_1$ | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0     | $d_1$ | 0 |

|   |   |   |   |   |   |   |   |   |   |   |   |   |   |       |       |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|-------|-------|
| × | × | × | × | × | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊠ | ⊠ | + | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| ⊠ | ⊠ | ⊠ | ⊠ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0 | 0 | $d_1$ | 0     |
| ⊠ | ⊠ | ⊠ | ⊠ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | $d_2$ |

|   |   |   |   |   |   |   |   |   |   |   |   |   |   |       |       |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|-------|-------|
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊗ | ⊗ | + | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| × | × | × | × | × | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | $d_1$ | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0 | 0 | 0     | $d_2$ |



|   |   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|
| × | × | × | × | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0 |

|   |   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| 0 | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 |
| 0 | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 |
| 0 | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0 |

|   |   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| 0 | 0 | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 |
| 0 | 0 | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 |
| 0 | 0 | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0 |

|   |   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| × | × | × | × | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | 0 | 0     | 0     | 0     | 0 |
| 0 | 0 | 0 | ⊗ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 |
| 0 | 0 | 0 | ⊗ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 |
| 0 | 0 | 0 | ⊗ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0 |



|   |   |   |   |   |   |   |   |   |   |   |       |       |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|-------|---|
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| × | × | × | × | 0 | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| × | × | × | + | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0     | 0 |
| 0 | 0 | 0 | ⊗ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0     | $d_1$ | 0     | 0     | 0 |
| 0 | 0 | 0 | ⊗ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0     | 0     | $d_2$ | 0     | 0 |
| 0 | 0 | 0 | ⊗ | ⊠ | ⊠ | ⊠ |   | 0 | 0 | 0 | 0     | 0     | 0     | $d_3$ | 0 |

|   |   |   |   |   |   |   |   |   |   |   |       |       |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|-------|---|
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | 0 | 0 | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | $d_1$ | 0     | 0     | 0 |
| 0 | 0 | 0 | 0 | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_2$ | 0     | 0 |
| 0 | 0 | 0 | 0 | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | $d_3$ | 0 |

|   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |       |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|-------|
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | 0 | 0 | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊕ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 | 0     |
| 0 | 0 | 0 | 0 | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_2$ | 0 | 0     |
| 0 | 0 | 0 | 0 | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | $d_3$ |

|   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |       |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|-------|
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | 0 | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | 0 | 0 | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 | 0     |
| 0 | 0 | 0 | 0 | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_2$ | 0 | 0     |
| 0 | 0 | 0 | 0 | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | $d_3$ |

$$\begin{array}{cccccccccccccccc}
\times & \times & \times & \boxtimes & \boxtimes & \boxtimes & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \boxtimes & \boxtimes & \boxtimes & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\times & \times & \times & \boxtimes & \boxtimes & \boxtimes & 0 & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & 0 & + & 0 & 0 & 0 & d_1 & 0 & 0 & 0 & 0 \\
\boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & 0 & & 0 & 0 & 0 & 0 & d_2 & 0 & 0 & 0 \\
\boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & d_2 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & d_3
\end{array}$$

|   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |       |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|-------|
| × | × | × | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | 0 | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊕ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0 | 0     |
| 0 | 0 | 0 | 0 | 0 | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | $d_3$ |

|   |   |   |   |   |   |   |   |   |   |   |       |       |       |       |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|-------|
| × | × | × | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | 0 | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | 0 |   | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0     |
| 0 | 0 | 0 | 0 | 0 | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | $d_3$ |

|   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |       |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|-------|
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | $d_3$ |



|   |   |   |   |   |   |   |   |   |   |   |       |       |       |   |       |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|---|-------|
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0 | 0     |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊞ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0 | $d_4$ |

|   |   |   |   |   |   |   |   |   |   |   |       |       |       |       |   |
|---|---|---|---|---|---|---|---|---|---|---|-------|-------|-------|-------|---|
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| × | × | × | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | + | 0 | 0 | 0 | $d_1$ | 0     | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | $d_2$ | 0     | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | $d_3$ | 0     | 0 |
| ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ | ⊗ |   | 0 | 0 | 0 | 0     | 0     | 0     | $d_4$ | 0 |

## A second algorithm

Before the last step of the first algorithm:

$$\begin{array}{cccccccccccccccc} \times & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & d_1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & d_2 & 0 & 0 & 0 & 0 & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & + & 0 & 0 & 0 & d_3 & 0 & 0 & 0 & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & d_4 & 0 & 0 & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & d_5 & 0 & 0 \\ \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & 0 & d_6 & 0 \end{array}$$

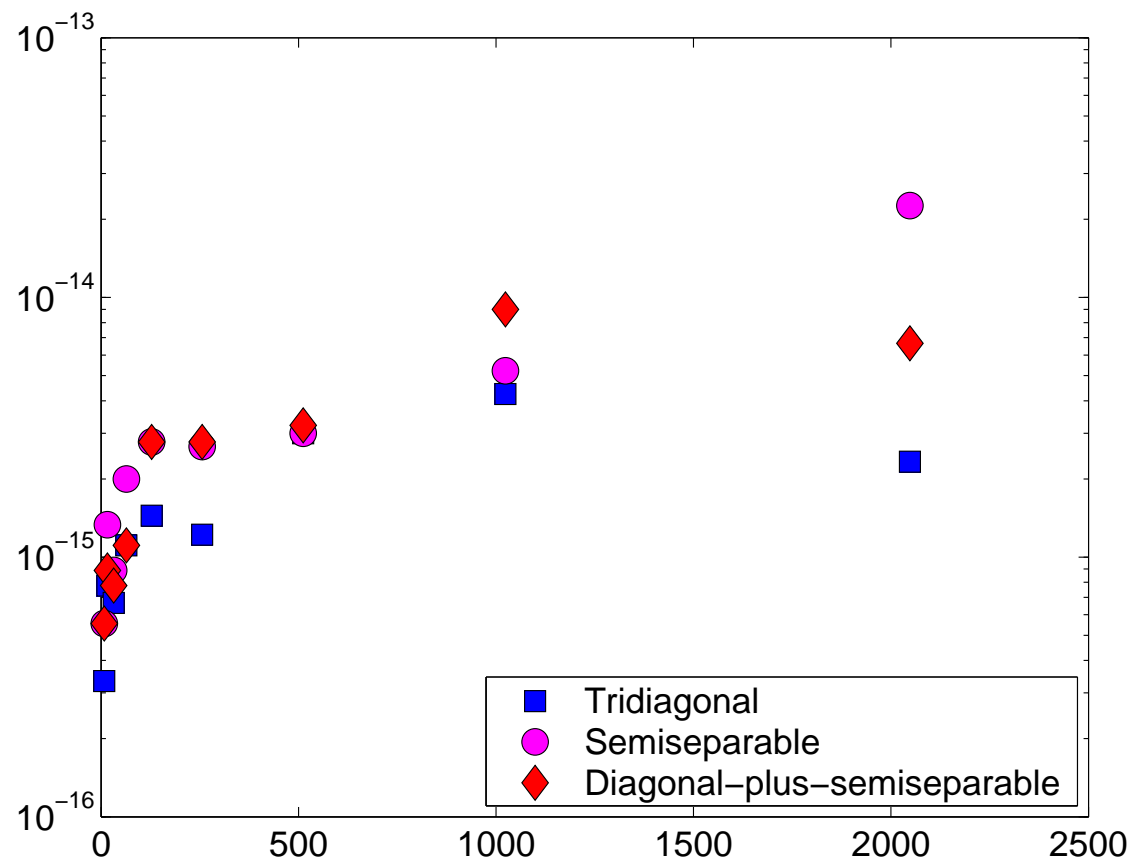
When applying the **first algorithm** starting with  $\mathbf{D} = [\mathbf{d}_2, \mathbf{d}_3, \dots, \mathbf{d}_n, \star]$  with  $\star$  an arbitrary element, instead of  $[\mathbf{d}_1, \mathbf{d}_2, \dots, \mathbf{d}_n]$ , we get the following situation before the last step:

$$\begin{array}{cccccccccccccccc}
 \times & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & d_2 & 0 & 0 & 0 & 0 & 0 & 0 \\
 \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & d_3 & 0 & 0 & 0 & 0 & 0 \\
 \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & + & 0 & 0 & 0 & d_4 & 0 & 0 & 0 & 0 \\
 \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & d_5 & 0 & 0 & 0 \\
 \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & d_6 & 0 & 0 \\
 \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & \boxtimes & & 0 & 0 & 0 & 0 & 0 & 0 & d_7 & 0
 \end{array}$$

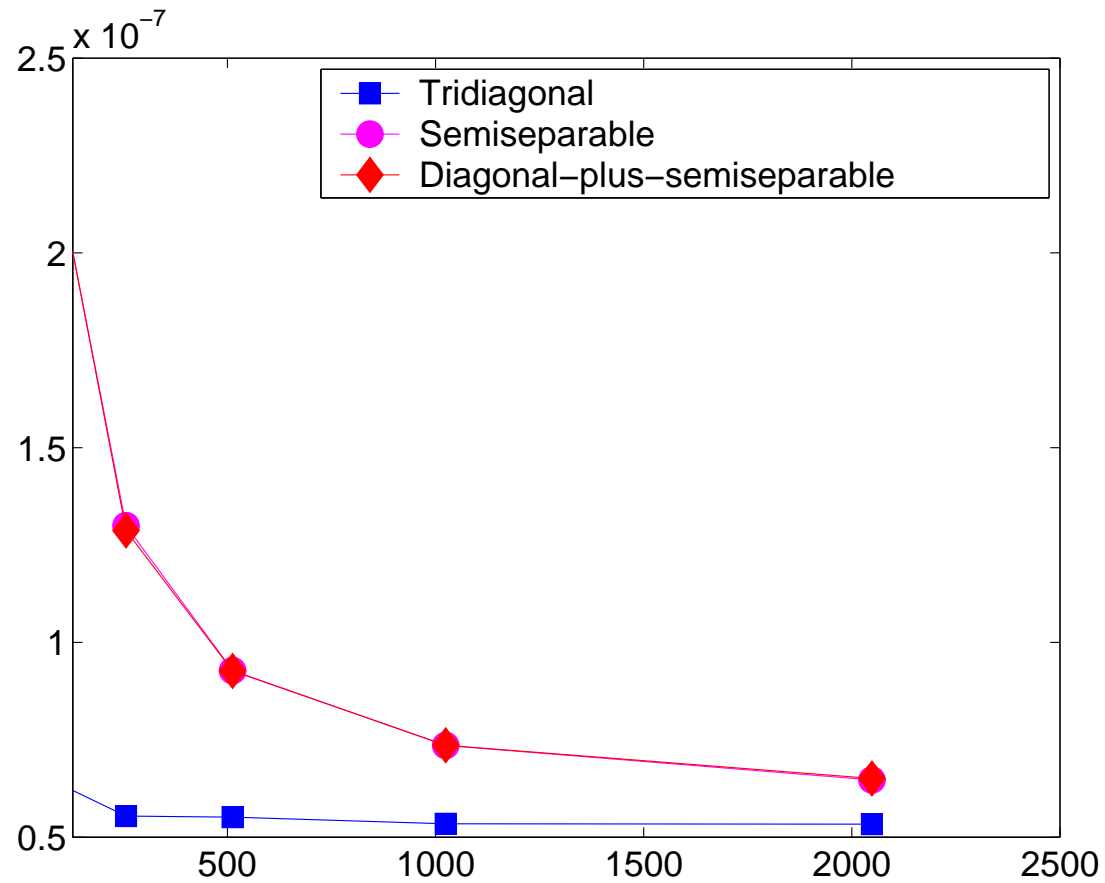


Any arbitrary symmetric matrix can be transformed into a symmetric diagonal-plus-semiseparable one with free choice of the diagonal by means of an orthogonal similarity transformation  $Q$  such that  $Qe_1 = e_1$ .

## II. Accuracy



### III. Computational complexity

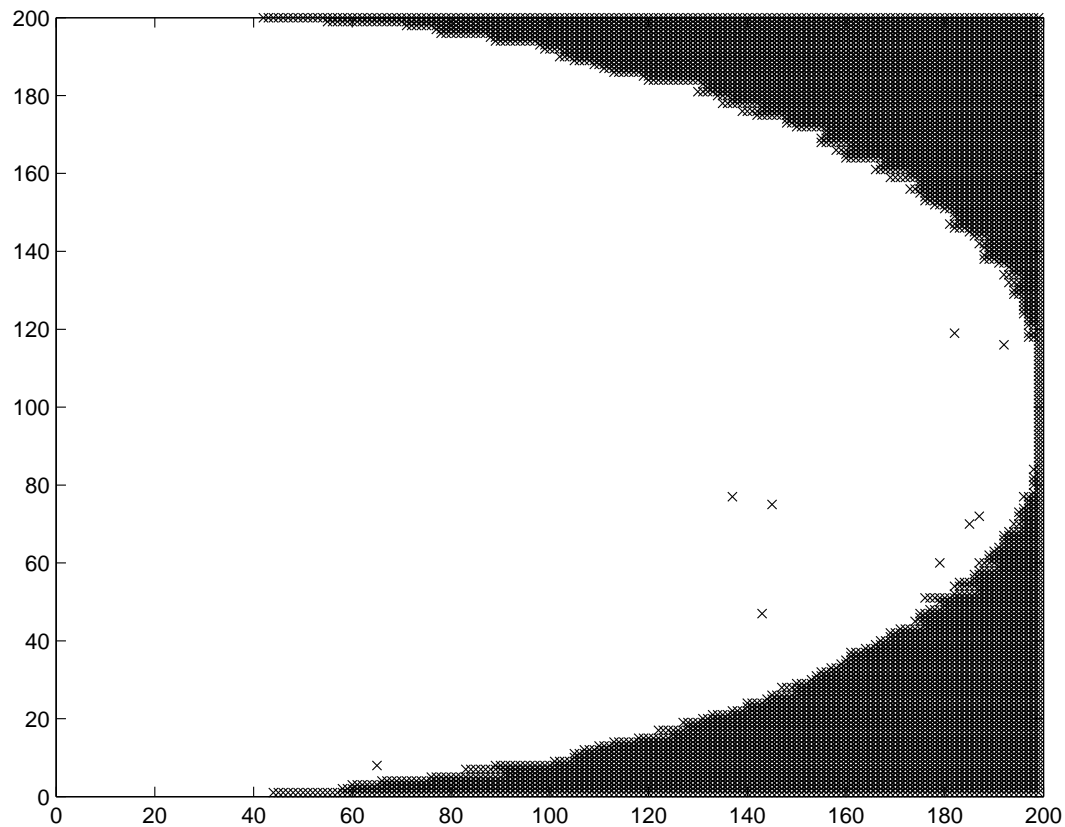




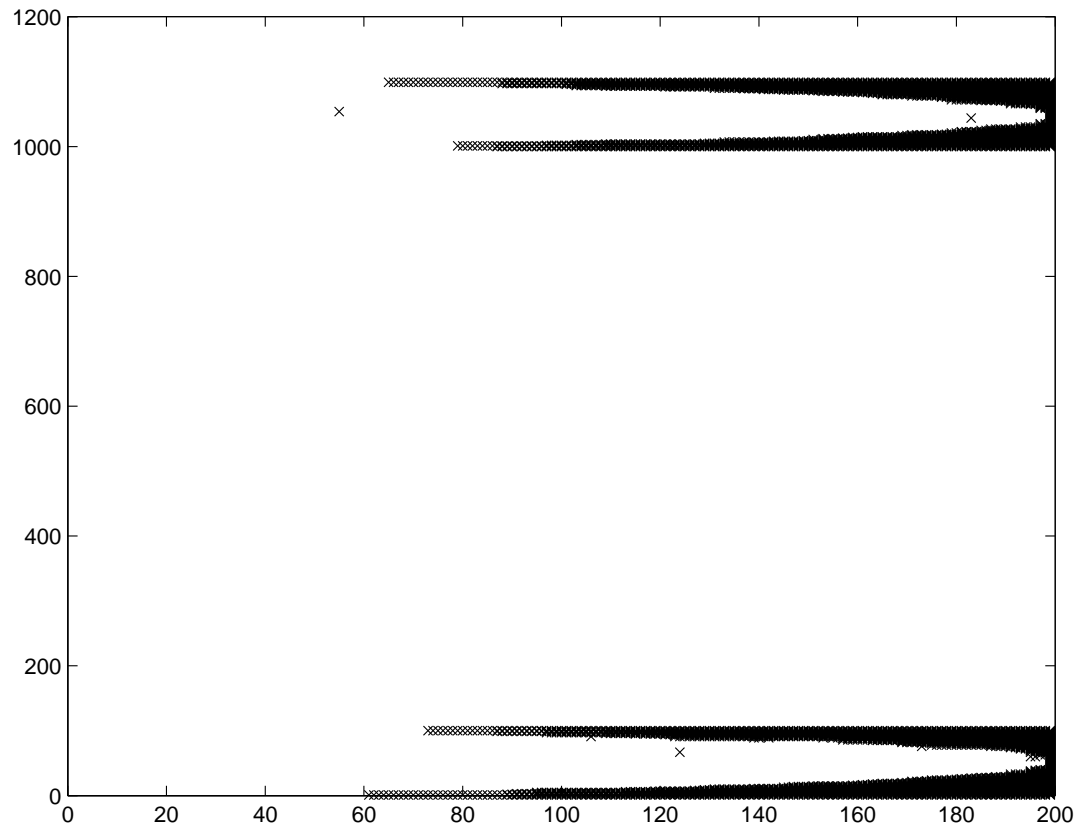
IV. Convergence behavior of reduction algorithm  
into diagonal-plus-semiseparable form

## For the reduction to semiseparable form

Eigenvalues are equidistant **1 : 200**.



Eigenvalues 1 : 100 and 1000 : 1100.



## For the reduction to diagonal-plus-semiseparable form

### Some notation

$$\begin{aligned} A^{(0)} &= A \\ A^{(m)} &= Q_m^T A^{(m-1)} Q_m \\ &= \left( \begin{array}{c|c} A_m & R_1^T \\ \hline R_1 & (D + S)_m \end{array} \right) \\ &= Q_{1:m}^T A Q_{1:m} \end{aligned}$$

where  $(\mathbf{D} + \mathbf{S})_m$  is a square **diagonal-plus-semiseparable** matrix of dimensions  $(m + 1) \times (m + 1)$ .

## Lemma

$$\mathbf{Q}_{1:m} \langle \mathbf{e}_n \rangle = (\mathbf{A} - \mathbf{d}_m \mathbf{I})(\mathbf{A} - \mathbf{d}_{m-1} \mathbf{I}) \dots (\mathbf{A} - \mathbf{d}_1 \mathbf{I}) \langle \mathbf{e}_n \rangle,$$

for  $m = 1, 2, \dots$  and  $\mathbf{Q}_{1:0} = \mathbf{I}$ .

## Proof.

. For  $m = 0$  :  $Q_{1:0} \langle e_n \rangle = \langle e_n \rangle$  .

. Suppose the theorem is true for  $m - 1$ , i.e.,

$$Q_{1:m-1} \langle e_n \rangle = (A - d_{m-1}I) \dots (A - d_2I)(A - d_1I) \langle e_n \rangle .$$

The structure of  $Q_m^T A^{(m-1)}$  is of the form:

$$\begin{pmatrix} \times & \dots & \times & | & 0 & \dots & 0 \\ \vdots & & \vdots & | & \vdots & & \vdots \\ \times & \dots & \times & | & 0 & \dots & 0 \\ \hline \times & \dots & \times & | & \times & \dots & 0 \\ \vdots & & \vdots & | & \vdots & \ddots & \vdots \\ \times & \dots & \times & | & \times & \dots & \times \end{pmatrix} + Q_m^T \begin{pmatrix} 0 & & & | & & & \\ & \ddots & & | & & & \\ & & & | & 0 & & \\ \hline & & & | & d_1 & & \\ & & & | & & \ddots & \\ & & & | & & & d_m \end{pmatrix} \\ = H + Q_m^T D$$

Hence,

$$\begin{aligned} Q_m^T(A^{(m-1)}) &= H + Q_m^T D \\ Q_m^T(Q_{1:m-1}^T A Q_{1:m-1}) &= H + Q_m^T D \\ \Rightarrow A Q_{1:m-1} - Q_{1:m-1} D &= Q_{1:m} H \end{aligned}$$

Applying the former equality on  $\langle e_n \rangle$  and using the induction hypothesis, we derive that:

$$\begin{aligned} (A Q_{1:m-1} - Q_{1:m-1} D) \langle e_n \rangle &= Q_{1:m} H \langle e_n \rangle \\ (A Q_{1:m-1} - Q_{1:m-1} d_m I) \langle e_n \rangle &= Q_{1:m} \langle e_n \rangle \\ \Rightarrow (A - d_m I)(A - d_{m-1} I) \dots (A - d_1 I) \langle e_n \rangle &= Q_{1:m} \langle e_n \rangle \end{aligned}$$

## Lanczos-Ritz convergence behavior

### a) Lanczos-Ritz values

Because  $AQ_{1:m} = Q_{1:m}A^{(m)}$  equals:

$$A \left[ \overleftarrow{Q}_{1:m} \mid \overrightarrow{Q}_{1:m} \right] = \left[ \overleftarrow{Q}_{1:m} \mid \overrightarrow{Q}_{1:m} \right] \left( \begin{array}{c|c} A_m & R_1^T \\ \hline R_1 & (D + S)_m \end{array} \right).$$

Hence, the eigenvalues of  $(\mathbf{D} + \mathbf{S})_m$  are the Ritz-values of  $\mathbf{A}$  with respect to the subspace spanned by the columns of  $\overrightarrow{Q}_{1:m}$ .



## b) Connection with the Krylov subspace

### Some notation

$$\mathcal{K}_m = \langle \mathbf{e}_n, \mathbf{A}\mathbf{e}_n, \mathbf{A}^2\mathbf{e}_n, \dots, \mathbf{A}^m\mathbf{e}_n \rangle$$

$$\mathbf{Q}_{m+1} = \left( \begin{array}{c|c|c} \tilde{H} & h & hq^T \\ \hline 0 & \times & \times \quad \dots \quad \times \\ & 0 & \times \\ \vdots & \vdots & \ddots \\ 0 & 0 & 0 \quad \times \quad \times \end{array} \right) \begin{cases} \tilde{H} \in \mathbb{R}^{(n-m-1) \times (n-m-2)} \\ h \in \mathbb{R}^{(n-m-1) \times 1} \\ q \in \mathbb{R}^{(m+1) \times 1} \end{cases} .$$

We want to prove by induction that:

$$\text{span} \left( \text{col}(\vec{Q}_{1:m+1}) \right) = \mathcal{K}_{m+1}.$$

We have:

$$\begin{aligned} \vec{Q}_{1:m+1} &= [\overleftarrow{Q}_{1:m} | \overrightarrow{Q}_{1:m}] \left( \begin{array}{c|cccc} h & & & & \\ \hline \times & \times & \dots & & \times \\ 0 & \times & & & \\ \vdots & & \ddots & & \vdots \\ 0 & 0 & & \times & \times \end{array} \right). \\ &= \overleftarrow{Q}_{1:m} h[1, q^T] + \overrightarrow{Q}_{1:m} \left( \begin{array}{c|cccc} \times & \times & \dots & & \times \\ \hline 0 & \times & & & \\ \vdots & & \ddots & & \vdots \\ 0 & 0 & & \times & \times \end{array} \right). \end{aligned}$$

Because:

- $\text{span} \left( \text{col}(\overrightarrow{Q}_{1:m}) \right) = \mathcal{K}_m = \langle e_n, Ae_n, \dots, A^m e_n \rangle$
- $\overrightarrow{Q}_{1:m+1} \langle e_n \rangle = (A - d_{m+1}I) \dots (A - d_1I) \langle e_n \rangle$

$$\Rightarrow \overleftarrow{Q}_{1:m} h \in \mathcal{K}_{m+1} \setminus \mathcal{K}_m$$

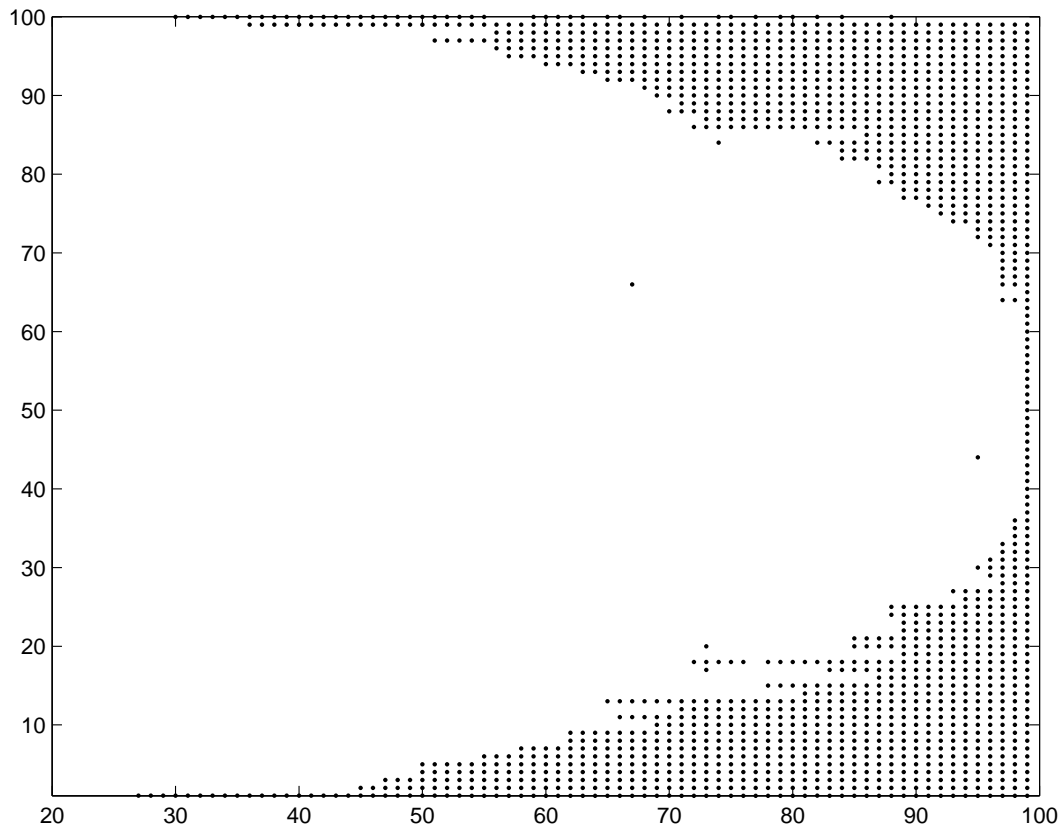
We get:

$$\text{span} \left( \text{col}(\overrightarrow{Q}_{1:m+1}) \right) = \mathcal{K}_{m+1} = \langle e_n, Ae_n, \dots, A^{m+1} e_n \rangle$$

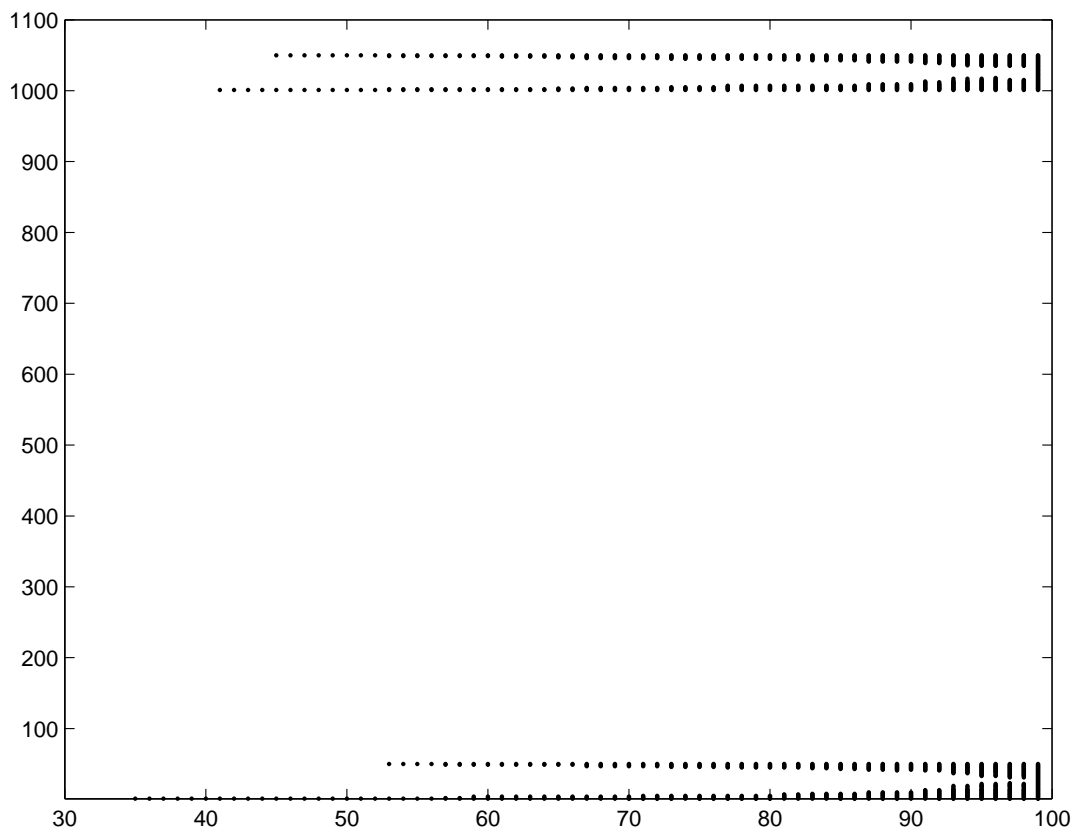
## Theorem

The eigenvalues of  $(\mathbf{D} + \mathbf{S})_m$ , the lower diagonal blocks that appear during the reduction algorithm, are the Lanczos-Ritz values of  $\mathbf{A}$  with respect to the Krylov subspace  $\mathcal{K}_m$ .

Eigenvalues are equidistant **1 : 100** and  
**d=random.**



Eigenvalues 1 : 50 and 10001 : 1050 and  
d=random.



## Subspace iteration

### The semiseparable case

Demo with two clusters of eigenvalues.

## The diagonal-plus-semiseparable case

### first step

$$\begin{aligned} A &= A^{(0)} = Q_1(Q_1^T A^{(0)}) \\ &= Q_1 \left( \left( \begin{array}{ccc|c} \times & \dots & \times & 0 \\ \vdots & & \vdots & \vdots \\ \times & \dots & \times & 0 \\ \hline \times & \dots & \times & \times \end{array} \right) + Q_1^T \left( \begin{array}{c|c} 0 & \\ \vdots & \\ & 0 \\ \hline & d_1 \end{array} \right) \right) \end{aligned}$$

Hence,

$$(A - d_1 I) \langle e_n \rangle = Q_1 \langle e_n \rangle = q_n^{(1)}.$$



Transformation of basis:

$$\mathbf{A}^{(1)} = \mathbf{Q}_1^T \mathbf{A} \mathbf{Q}_1$$

A vector  $\mathbf{y}$  in the old basis, becomes  $\mathbf{Q}_1^T \mathbf{y}$  in the new basis. This means that  $\mathbf{q}_n^{(1)}$  becomes  $\mathbf{Q}_1^T \mathbf{q}_n^{(1)} = \mathbf{e}_n$  and hence,  $(\mathbf{A} - d_1 \mathbf{I}) \langle \mathbf{e}_n \rangle$  becomes  $\langle \mathbf{e}_n \rangle$ .

*m*th step

$$(\mathbf{A} - d_m \mathbf{I}) \dots (\mathbf{A} - d_1 \mathbf{I}) \langle \mathbf{e}_{n-j}, \dots, \mathbf{e}_n \rangle = \langle \mathbf{q}_{n-m+1}^{(m)}, \dots, \mathbf{q}_n^{(m)} \rangle$$

for  $j = 0, \dots, m + 1$ .

## Conclusion

The reduction algorithm proposed in this talk in order to transform any symmetric matrix into a diagonal-plus-semiseparable one with free choice of the diagonal has

- A Lanczos-Ritz behavior - Krylov subspace
- Subspace iteration.

⇒ As soon as the Lanczos-Ritz values approximate some eigenvalues good enough, the subspace iteration starts converging.